

Eng. Research Bull.  
Faculty of Eng. & Tech.,  
Menoufia University  
Vol. VII Part II, 1985.

PP. 133-148.

EFFECT OF METALLURGICAL AND GEOMETRICAL  
PARAMETERS ON THE DEFORMATION RESISTANCE  
AND WORK OF DEFORMATION DURING HOT ROLLING  
OF SINGLE-AND TWO-PHASE BRASSES

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ABSTRACT:

The solution of all technological problems of metal working required information about the behaviour of material during plastic deformation.

The mean deformation resistance  $K_m$  and the specific work of deformation  $W_s$  are considered to be the most important measurable values during hot rolling.

In this work,  $K_m$  and  $W_s$  were experimentally determined and an attempt was made to correlate these values with: microstructure, phase and different geometrical values for single-phase  $\alpha$ -brass (70 Cu - 30 Zn) and two-phase  $\alpha + \beta$  brass (60 Cu - 40 Zn).

The strain rate and rolling temperature were kept constant at  $10 \text{ s}^{-1}$  and  $550^\circ\text{C}$  respectively.

It was found that  $K_m$  and  $W_s$ , for constant specimen thickness, increased with the amount of deformation  $\epsilon$ . In the examined range of  $\epsilon$  (up to 50 % per pass) no decrease in  $K_m$  due to dynamic softening was observed. At a constant  $\epsilon$ ;  $K_m$  and  $W_s$  showed a minimum with  $l_d/h_m$  then increased again. The results indicate that two-phase brass has a higher deformation resistance and work of deformation compared with single-phase brass.

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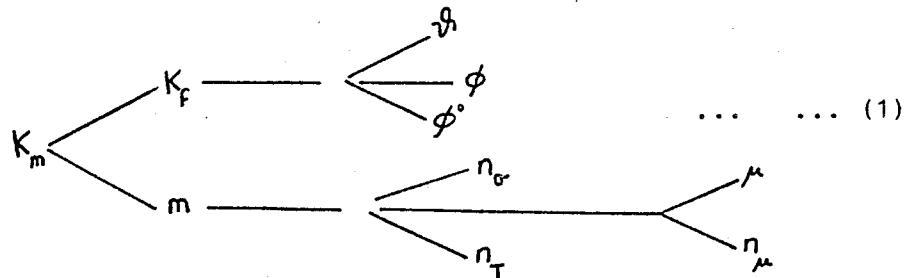
An explanation was given to declare the above results.

NOMENCLATURE:

$K_m$	mean deformation resistance	MPa
$W_s$	specific work of deformation	J/mm <sup>3</sup>
$\phi$	true strain	
$\phi^{\circ}$	true strain rate	s <sup>-1</sup>
$h_o$	initial height of specimen	mm
$h_f$	final height of specimen	mm
$\Omega$	rolling temperature	°C
$K_f$	constrained flow stress	MPa
$\Delta h$	reduction in height	mm
$\epsilon\%$	$(h_o - h_f) / h_o \cdot 100$	
$h_m$	mean height of specimen	mm
$R$	roll radius	mm
$b_o$	initial	} width of specimen mm
$b_m$	mean	
$b_f$	final	
$l_d$	projected length of the arc of contact $= \sqrt{R \cdot \Delta h}$	mm
$A_d$	area of deformed zone $= b_m \cdot l_d$	

INTRODUCTION:

The basic factors affecting  $K_m$  can be summarised as follows:



Where;

- m - a general function.
- $n_{\sigma}$  - stress distribution factor depending upon geometry of deformed zone.
- $n_T$  - front or backward tension (external force acting on the deformed metal at the entry of deformation zone).
- $\mu$  - friction coefficient.
- $n_{\mu}$  - influence of the parts of the metal outside the deformation zone.

A general solution of this function does not exist at the moment in the theory of plastic deformation. There are several particular solutions adapted to the specific process under study. The most popular approach, mainly for rolling, is the plane strain condition /1/.

According to Nadai /2/, the effect of the above mentioned factors on  $K_m$  can, in the general case, be expressed as:

$$dK_m = \frac{\partial K_m}{\partial \theta} d\theta + \frac{\partial K_m}{\partial \phi} d\phi + \frac{\partial K_m}{\partial \phi^{\circ}} d\phi^{\circ} + \frac{\partial K_m}{\partial t} dt \dots \dots (2)$$

where the fourth item of equation 2 considers the relaxation with the time t. The total work W required to produce a shape by plastic deformation can be divided into a number of components. The work of deformation  $W_d$  is the work required for homogeneous reduction by uniform deformation. Often, part of the total work is expended in redundant work  $W_r$ . The redundant, or internal - deformation, work is the energy expended in deforming a body but not involved in shape change. Finally, part of the total work must be used to overcome the frictional resistance at the interface between the forming tool and the metal.

$$W = W_d + W_r + W_f \dots \dots \dots (3)$$

A similar equation for  $K_m$  can be written as:

$$K_m = K_f + K_r + K_i \dots \dots \dots (4)$$

Where;

$K_r$  - frictional stress at the interface between metal and tool.

$K_i$  - redundant stress.

Fig. 1. illustrates the variation of  $K_r$ ,  $K_i$ , and  $K_m$  with the geometry of deformed zone (length of deformed zone  $l_d$ /mean height  $h_m$ ) at a constant  $K_f/3$ .

The effect of metallurgical parameters (grain size, type, size and shape of phases) on the deformation resistance has been studied by several investigators.

Kaneko and Horiucki /4/ examined the effect of grain size  $D$  and distance between dendrites  $d$  on the deformation resistance of aluminium and copper alloys during hot torsion at  $450^\circ\text{C}$  and strain rate of  $5 \text{ s}^{-1}$ .

The following dependence was arrived at:

$$K_m = K_0 + Kd^{-1/2} + KD^{-1/2} \dots \dots \dots (5)$$

Köpf /5/ investigated the effect of chemical composition and solution heat treatment on the deformation resistance of Al-Mg and aluminium-bronzes. He considered that precipitation hardening effect is appreciated as one of the most important strengthening mechanisms which increases the deformation resistance. Heinemann /6/ found that  $K_m$  increased with decreasing rolling temperature and increasing reduction per pass during hot rolling of several aluminium and copper alloys. A similar results have been concluded by Höptner on Al & Al-Mg alloy during hot compression /7/.

In this work an attempt was made to study the effect of both parameters: metallurgical and geometrical on  $K_m$  and  $W_s$  of single-phase  $\alpha$  - brass and two-phase  $\alpha+\beta$  brass.

Since a limited experimental information is available on the deformation of two-phase alloys, it is aimed in this work to present results about the deformation resistance of single-and two-phase structure during hot working.

EXPERIMENTAL PROCEDURE:

The alloys were prepared from highly pure copper and zinc and melted under vacuum.

The chemical composition of the alloys was depicted (in wt. %) in the following table.

Alloy	Cu	Zn	Fe	Sn	Al	Mn	Pb
A	69	30.5	0.1	0.1	0.1	0.1	0.03
B	59	40	0.2	0.2	0.1	0.2	0.3

Alloy A consists mainly from single phase  $\alpha$  while alloy B contains two-phase structure  $\alpha + \beta$  as shown in the micrographs (Fig. 2) of the as-cast structure at room temperature.

Three different specimen thicknesses 10 , 20 and 30 mm, were heated in an electric resistance furnace at a temperature of 550°C for four hours.

At the rolling temperature of 550°C, the two alloys were found to have the same structures as depicted in Fig. 2.

Rolling was performed at a two-high, pull-over mill with a roll radius of 180 mm. To avoid the effect of strain rate on  $K_m$  and  $W_s$ , the experiments were carried out at a constant mean value of  $\dot{\phi}^\circ$  equal to  $10 \text{ s}^{-1}$ . Accordingly, the number of revolutions per minute (n) have to be corrected for each

reduction per pass  $\epsilon$  and  $h_0$  in order to keep  $\phi^\circ$  constant.

$$n = \frac{\phi^\circ \cdot 60 \cdot \sqrt{R \cdot \Delta h}}{2 \pi R \cdot \phi} \dots \dots \dots (6)$$

Fig. 3. shows the values of  $n$  required to give constant  $\phi^\circ$  for different  $\epsilon$  &  $h_0$ . The lower and upper rolls were constructed to be fitted with a tungsten radial pen which transmitted the pressure to a dynamometer. Signals were transmitted from dynamometer to a simple resistance amplifiers then to oscillograph.

$K_m$  was caculated as follows:

$$K_m = F / A_d \quad \text{MPa} \quad \dots \dots \dots (7)$$

$W_s$  was calculated, assuming that the exit velocity of rolled specimen equals the initial roll velocity, by the equation:

$$W_s = T / (b_m \cdot h_1 \cdot R) \quad \text{J mm}^{-3} \quad \dots \dots \dots (8)$$

Where  $T$  is the total torque in J.

EXPERIMENTAL RESULTS AND DISCUSSION

It was found that  $K_m$  and  $W_s$  for both A & B alloys increased with  $\epsilon$  at a constant  $h_0$  (Figs. 4 to 7). The rate of increase of  $K_m$  and  $W_s$  was higher for a thin specimen. In the examined range of  $\epsilon$  (up to 50% per pass),  $K_m$  and  $W_s$  did not decrease due to the dynamic softening mechanisms. Metallographic examination of rapidly quenched A & B specimens after different  $\epsilon$  showed that only dynamic recovery was acting during this high temperature of deformation. The extent of recovery was higher for the two-phase structure (Alloy B) which means a retardation of recrystallisation. This result can be explained on the basis that the second phase blocks slip so that plastic deformation is not uniform in the matrix. This result was in agreement with several

works on aluminium and copper alloys /8 , 9 & 10/.

A comparison of the behaviour of alloys A & B clearly demonstrates the dependence of  $K_m$  and  $W_s$  on chemical composition and consequently on grain size in addition to size, shape, number and distribution of the second-phase particle, the strength, ductility and strain-hardening behavior of the matrix and second phase. It is almost impossible to vary these factors independently in experiments.

A higher  $K_m$  - and  $W_s$  - values were reported for B alloy.

The effect of  $\epsilon$  and  $h_o$  on  $K_m$  and  $W_s$  can be clarified by the complex interaction of the following factors:

- Strengthening of the material during deformation,
- Variation of the geometry of the deformed zone,  $l_d/h_m$  was little affected by the increase of  $\epsilon$  for a thick specimen compared to a thin one,
- Cooling of rolled specimen, which depends upon height of specimen, amount of deformation (contact area) and number of revolutions (time of contact) Fig. 2.

Regarding the effect of the geometry of deformed zone on  $K_m$  and  $W_s$  (Figs. 4,5 & 6,7) the following points can be deduced:

At a constant  $\epsilon$  :  $K_m$  &  $W_s$  decreased to a minimum value then increased again. This minimum has been shifted to a higher values of  $l_d/h_m$  with increasing  $\epsilon$  .

Several works on steel showed that  $K_m$  attained a minimum at  $l_d/h_m \approx 1$ . An exact explanation of this result cannot be given here.

At constant  $h_o$  : Approximately linear relationships between  $K_m$  and  $W_s$  vs.  $l_d/h_m$  were found. Thin specimens have a higher rate of increase of  $K_m$  - and  $W_s$  - values.

## CONCLUSION

The results of the present investigation can be summarised as follows:

1. The mean deformation resistance  $K_m$  and the specific work of deformation  $W_s$  were found to be affected by: initial height of specimen,  $l_d/h_m$  as a ratio of the length of deformed zone to the mean height of specimen, and amount of deformation.

In addition, both the deformation resistance and work of deformation depend on the metallurgical parameters which include: chemical composition of the alloy, grain size and shape, size and distribution of  $\alpha$ - phase in  $\beta$ - matrix.

2. At constant amount of deformation; the deformation resistance and work of deformation showed a minimum with  $l_d/h_m$ . While at constant initial height of specimen  $h_o$ , the curves showed a linear relation that can be ascribed by a simple mathematical equation.

## ACKNOWLEDGEMENT:

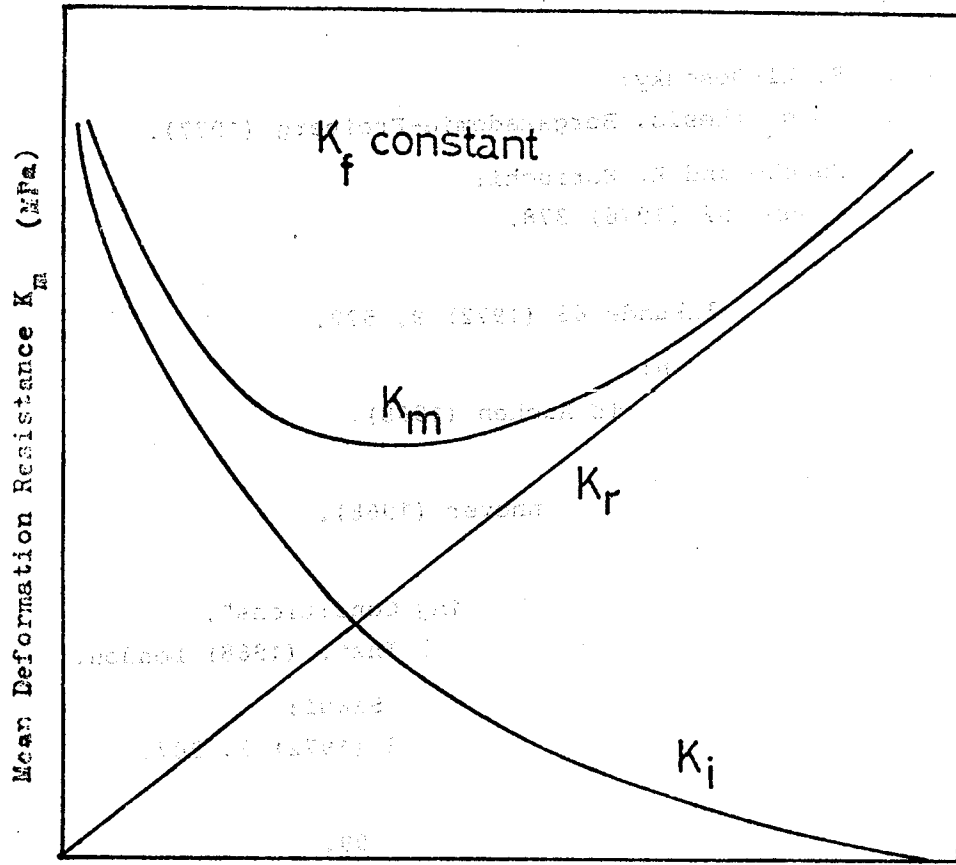
The author is indebted to Prof. Dr. A. A. Nasser for his valuable discussions and encouragement throughout this research.

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Length of deformed zone  $L_d$  / mean height  $h_m$

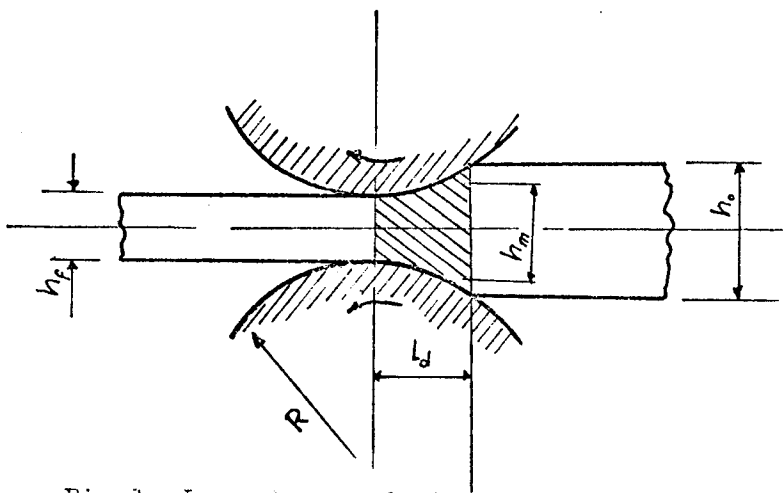
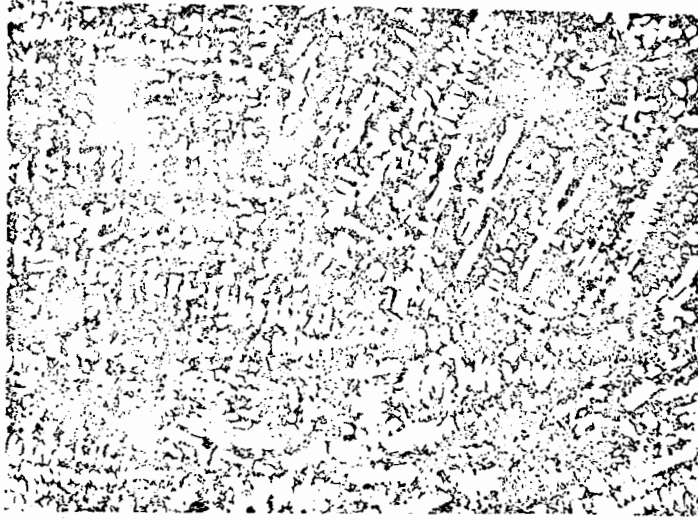
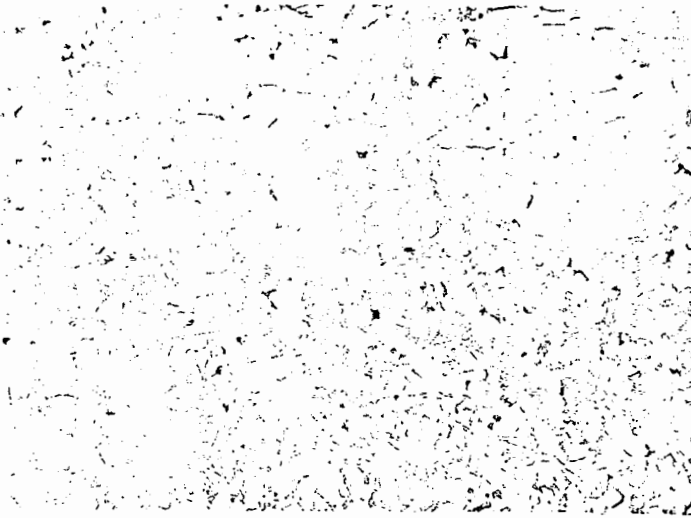


Fig.1: Dependence of the deformation resistance on the geometry of deformed zone



Alloy B



Alloy A

Fig.2 Microstructures in the as-cast condition at room temperature (400 X)

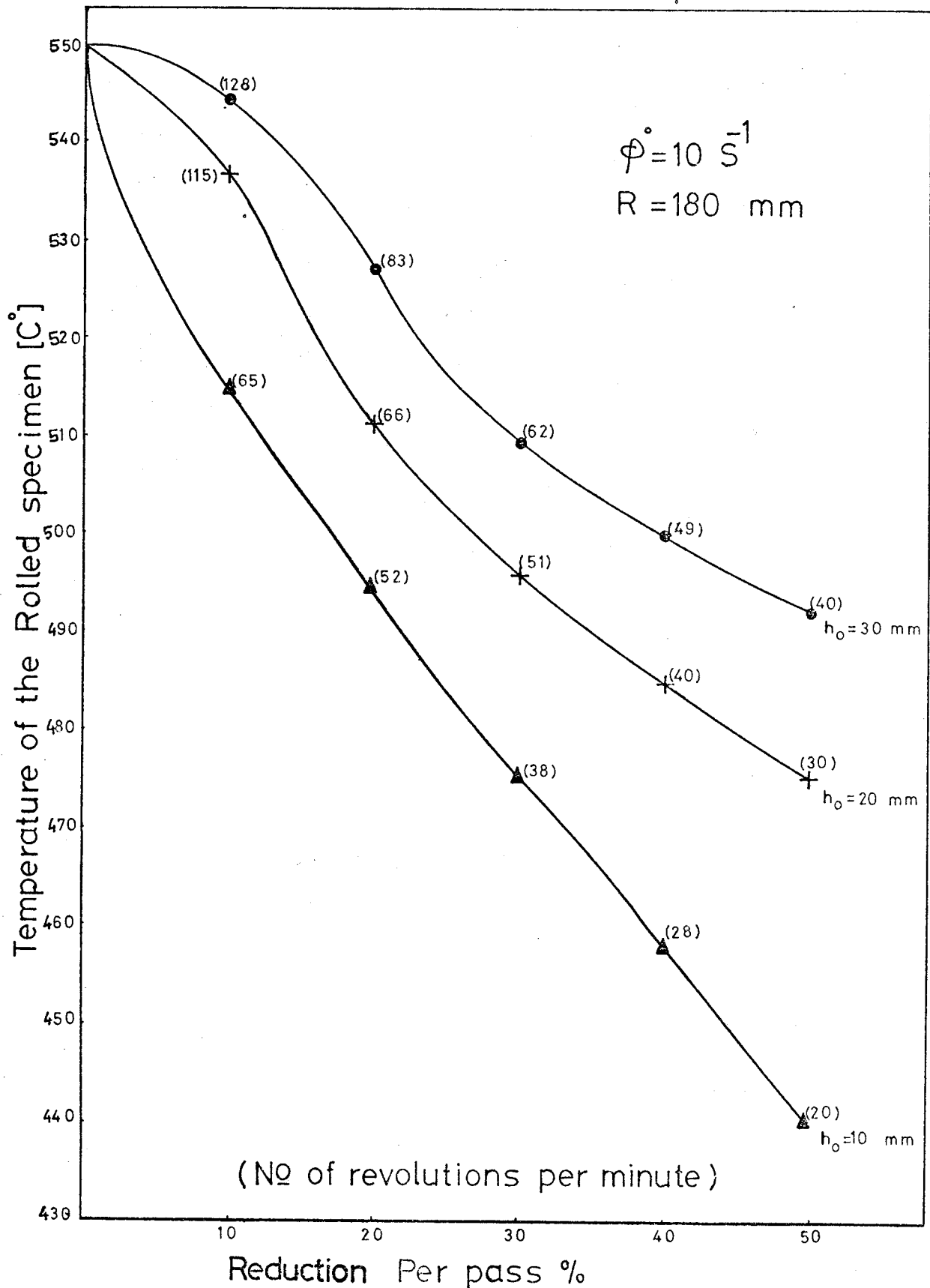


Fig.3: Temperature descent of the rolled specimen during rolling

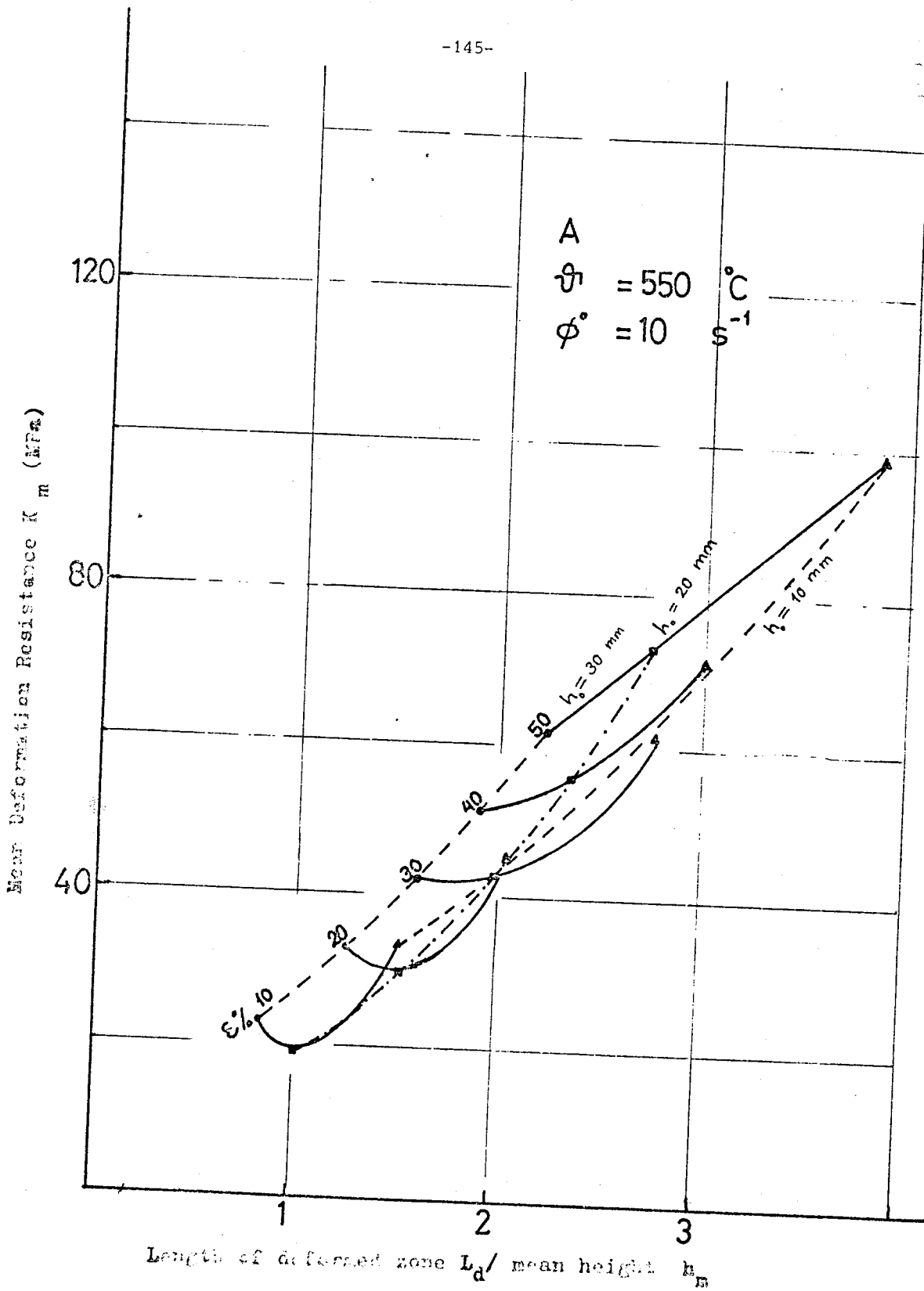
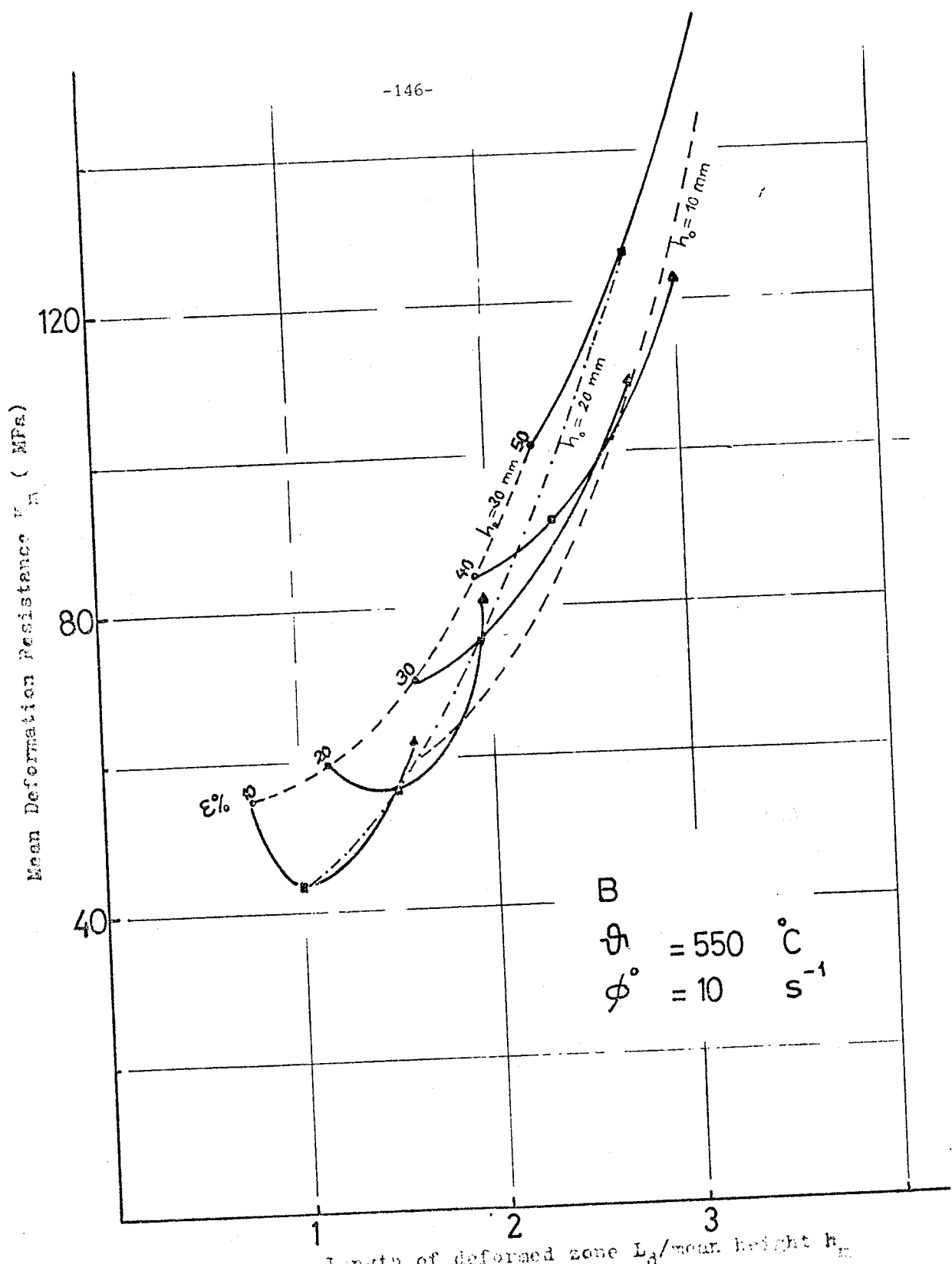


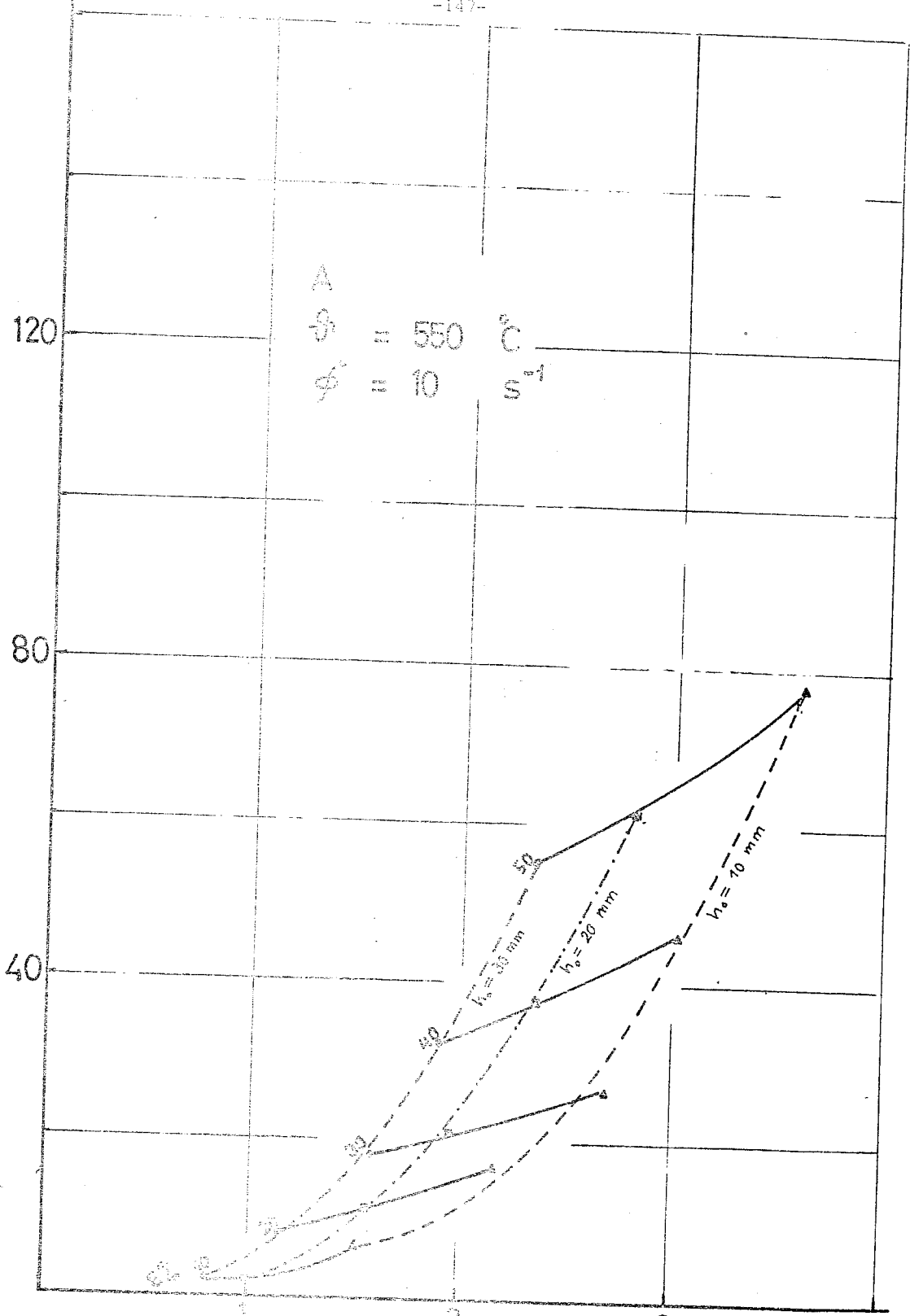
Fig.4: Dependence of  $K_m$  on  $L_d / h_m$  for different amounts of deformation  $\epsilon$  and initial heights of rolled specimens  $h_0$ .



B  
 $\dot{\vartheta} = 550\text{ }^\circ\text{C}$   
 $\phi^\circ = 10\text{ s}^{-1}$

Fig.5: Dependence of  $K_m$  on  $L_d / h_m$  for different amounts of deformation  $\epsilon$  and initial heights of rolled specimens  $h_0$ .

Specific Work of Deformation  $W_s$  J. mm<sup>-3</sup> · 10<sup>-3</sup>



A  
 $\dot{\phi} = 550$  C  
 $\dot{\phi} = 10$  S<sup>-1</sup>

length of deformed part  $l_0 / h_0$  / mm. height  $h_0$

Fig.6: Dependence of  $W_s$  on  $l_0 / h_0$  for different amounts of deformation  $\epsilon$  and initial heights of rolled specimens  $h_0$ .

Specific Work of Deformation  $W_s$ , J. mm<sup>-3</sup> · 10<sup>-3</sup>

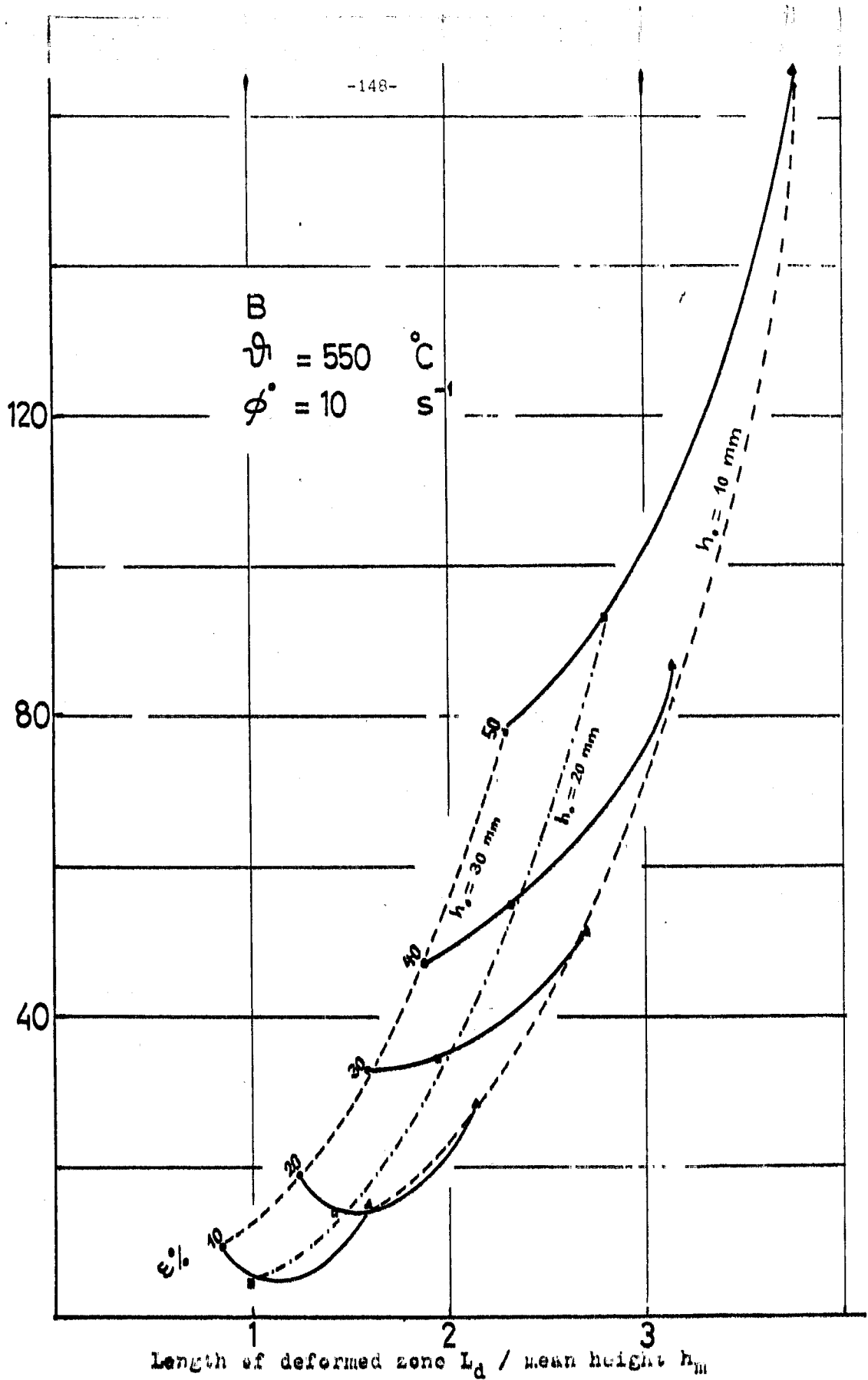


Fig. 7: Dependence of  $W_s$  on  $L_d / h_m$  for different amounts of deformation  $\epsilon$  and initial heights of rolled material  $h_0$ .