



Exam of: Digital Control Sys. For 2<sup>nd</sup> yr Computers Eng. & Systems Dept. Students

**Question1: Explain**

[20 Marks]

- Digital controllers present significant advantages over classical analog controllers.
- The need for reconstruction process (holding), the construction of the most common holding device and its disadvantages.
- The aliasing phenomenon.

**Question 2:**

[15 Marks]

- Solve the following difference equation:  
 $f(k+2) - 3f(k+1) + 2 f(k) = 1 , f(0) = f(1) = 0$

**Question 3:**

[20 Marks]

- Study the transient response of the system shown in fig. 2, with a **unit step input** and  $T=1$  sec., Find:
 

1- damping ratio $\zeta$	2- natural undamping frequency $\omega_n$
3- Peak time $t_p$	4- settling time $t_s$
5- Maximum overshoot $M_p\%$	6- steady state error
7- time constant $\tau$	
- Study the effect of sampling on the system's stability (i.e. study analog system then comment on system stability after introducing a sampler).

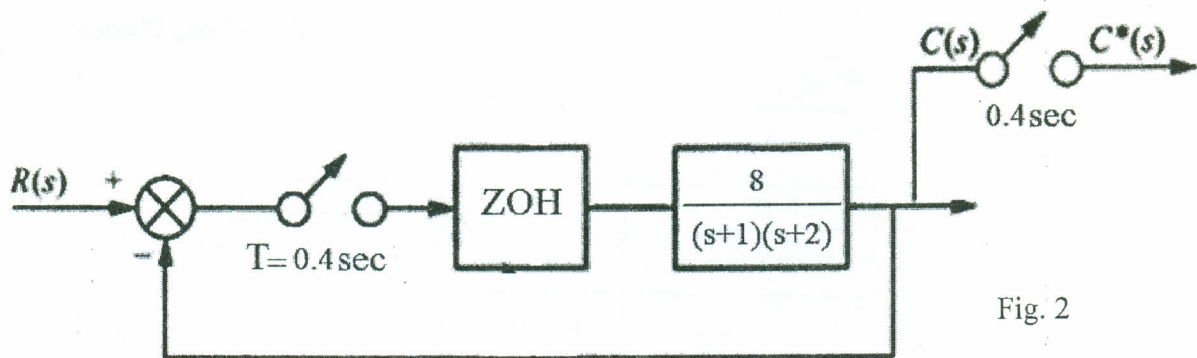


Fig. 2

Z-Transform Table

Laplace Transform	Time function	Z-Transform
1	Unit impulse $\delta(t)$	1
$\frac{1}{s}$	Unit step $u(t)$	$\frac{Z}{Z-1}$
$\frac{1}{1-e^{-Ts}}$	$\delta_T(t) = \sum_{n=0}^{\infty} \delta(t-nT)$	$\frac{Z}{Z-1}$
$\frac{1}{s^2}$	$t$	$\frac{TZ}{(Z-1)^2}$
$\frac{1}{s^3}$	$\frac{t^2}{2}$	$\frac{T^2 Z(Z+1)}{Z(Z-1)^3}$
$\frac{1}{s^{n+1}}$	$\frac{t^n}{n!}$	$\lim_{a \rightarrow 0} \frac{(-1)^n}{n!} \frac{\partial^n}{\partial a^n} \left[ \frac{Z}{2-e^{-at}} \right]$
$\frac{1}{s+a}$	$e^{-at}$	$\frac{Z}{Z-e^{-aT}}$
$\frac{1}{(s+a)^2}$	$te^{-at}$	$\frac{TZe^{-aT}}{(Z-e^{-aT})^2}$
$\frac{a}{s(s+a)}$	$1-e^{-at}$	$\frac{(1-e^{-aT})Z}{(Z-1)(Z-e^{-aT})}$
$\frac{\omega}{s^2 + \omega^2}$	$\sin \omega t$	$\frac{Z \sin \omega T}{Z^2 - 2Z \cos \omega T + 1}$
$\frac{\omega}{(s+a)^2 + \omega^2}$	$e^{-at} \sin \omega t$	$\frac{Ze^{-aT} \sin \omega T}{Z^2 - 2Ze^{-aT} \cos \omega T + e^{-2aT}}$
$\frac{s}{s^2 + \omega^2}$	$\cos \omega t$	$\frac{Z(Z - \cos \omega T)}{Z^2 - 2Z \cos \omega T + 1}$
$\frac{s+a}{(s+a)^2 + \omega^2}$	$e^{-at} \cos \omega t$	$\frac{Z^2 - Ze^{-aT} \cos \omega T}{Z^2 - 2Ze^{-aT} \cos \omega T + e^{-2aT}}$